# MC4X15A

# **Universal Motor Controller**

Revision 1.0 / 14.May.2017

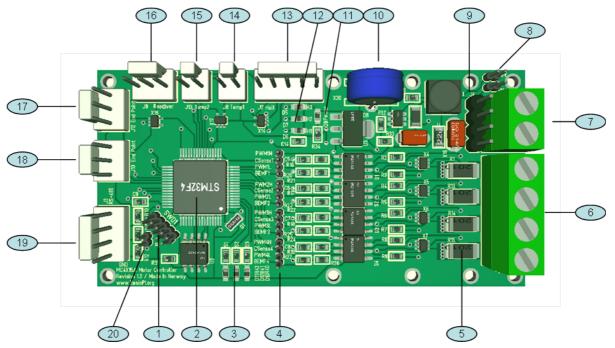
MC4X15A is a Motor Controller based on 4 separate half-bridge drivers capable of driving 12-24V @ 15A each. Peak current can be larger. The controller is equipped with a powerfully STM32 M4, RS485, temp sensors, end stops, resolver, hall sensors, current sensors and voltage/bemf sensors to support a wide variety of applications.

- Solenoid Driver
- DC Motor Driver
- Stepper Motor Driver
- Brushless 3-Phase Motor Driver

#### Content

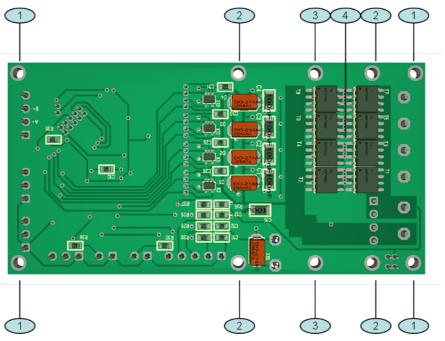
- STM32F405RG, 32-bit ARM M4, 168Mhz RISC MCU
- 1Mb Flash, 192Kb SRAM
- SWD Adapter
- 3 status led's.
- 4 separate half-bridge drivers supporting 12-24V @15A each. All with current sensors and BEMF sensors.
- High Speed RS-X/RS485
- Hall sensors with separate leds.
- Input Voltage Sensor.
- 2 x Temperature sensors.
- 2 x End Stops
- 1 x Resolver input.
- Separate 3.3V «stay-alive» supercap.
- Adapter for battery or capacitors.
- Size 80 x 40mm. Height depending on adapter board.

# MC4X15A Top Side Annotation



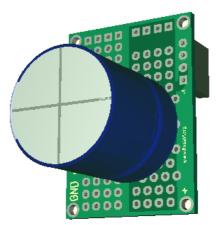
| #  | Description   |  |  |  |
|----|---|--|--|--|
| 1  | BasicPI SWD connector with SWD, Reset, Boot 3.3V & UART.  |  |  |  |
| 2  | STM32F405RG. 32 bit ARM MCU w/1MbFlash, 192KbSRAM and M4 floating point support. Can be replaced with STM32F105RB.        |  |  |  |
| 3  | Status leds.  |  |  |  |
| 4  | Test points or external connection to all BEMF, Current and PWM signals.  |  |  |  |
| 5  | Current shunts.   |  |  |  |
| 6  | 4 x Half Bridge PWM output.   |  |  |  |
| 7  | Power Input 12-24V  |  |  |  |
| 8  | 1.27 pitch Jumper for 12V/24V Input   |  |  |  |
| 9  | 2.54 pitch power adapter for battery, capacitor and break resistors.  |  |  |  |
| 10 | 3.3V Super capacitor.   |  |  |  |
| 11 | Power Led.  |  |  |  |
| 12 | Hall Sensor Leds.   |  |  |  |
| 13 | Hall Sensor Connector.  |  |  |  |
| 14 | Temperature Sensor Connector. Shown on top here, but can be mounted inwards on the back for sensors between the HEXFET's. |  |  |  |
| 15 | Temperature Sensor 2.   |  |  |  |
| 16 | Resolver input. Basically an analogue pin with 6V suppression diode.  |  |  |  |
| 17 | End point connector.  |  |  |  |
| 18 | End point connector.  |  |  |  |
| 19 | RS-485 Connector  |  |  |  |
| 20 | Terminal jumper for RS-485.   |  |  |  |

## MC4X15A Back Side Annotation



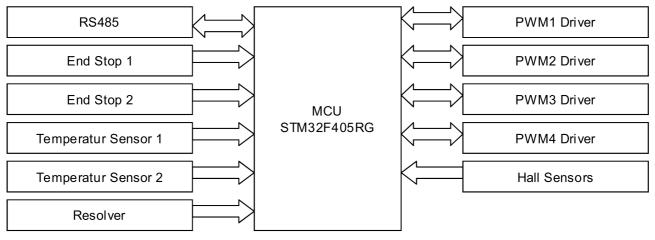
|  | # | Description   |  |  |
|--|---|---|--|--|
|  | 1 | 4 xM2 Mounting holes for external mounting.   |  |  |
|  | 2 | 4 x M2 mounting holes for Battery/Capacitor adapter board.                                  |  |  |
| 3 2 extra M2 Mounting holes for heatsink. Must share 2 mounting holes with the adapter board |   | 2 extra M2 Mounting holes for heatsink. Must share 2 mounting holes with the adapter board. |  |  |
|  | 4 | 8 x HEXFET's mounted on the back with M2 screw holes to fit small heatsink.                 |  |  |

## **Capacitor Adapter Board**



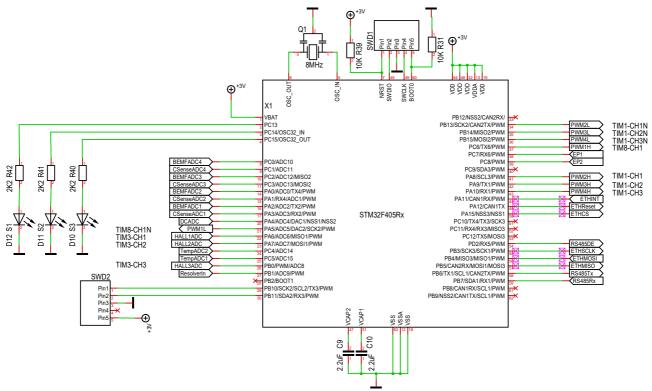
The Capacitor Adapter Board is basically a specialized vero board designed to add hole through capacitors as needed. This needs to be adapted to the motor in use.

# **Functional Block Diagram**



## Schematics

MCU



The schematics above show the MCU itself. An 8Mhz Murata ceramic x-tal, SWD connector and 3 x LED's. The MCU connection points are listed in the table below.

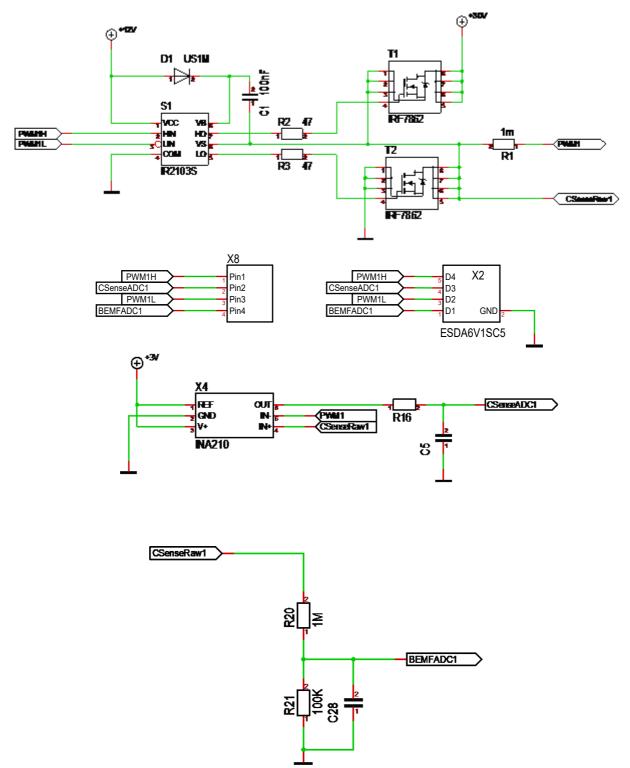
| X-Tal          | Pin 5 & 6   | Ceramic Murata with a small all-in-one 3mm package is<br>used to save space. Using a ceramic crystal is much<br>better than the internal RF crystal, but not as accurate as<br>a proper crystal. |  |
|----------------|---|--|--|
| VCAP           | Pin 31 & 47<br>connected to a 2.2uF<br>capacitor. | This must be replaced with 00hm resistors for STM32F105Rx.   |  |
| SWD            | 7 NRST  |  |  |
|                | 48 SWDIO  |  |  |
|                | 49 SWCLK  |  |  |
|                | 60 BOOT0  |  |  |
|                | 29 TX3  |  |  |
|                | 30 RX3  |  |  |
| PWM w/Sensors  | 37 PWM1H  | PC6 TIM8-CH1   |  |
|                | 21 PWM1L  | PA5 TIM8-CH1N  |  |
|                | 16 BEMFADC1                                       | PA2 - ADC2   |  |
|                | 17 CSenseADC1                                     | PA3 - ADC3   |  |
| PWM2 w/Sensors | 41 PWM2H  | PA8 - TIM1-CH1   |  |

|  | 34 PWM2L | PB13 - TIM1-CH1N |
|--|----------|------------------|
|--|----------|------------------|

|                   | 14 BEMFADC2   | PA0 - ADC0              |
|-------------------|---------------|-------------------------|
|                   | 15 CSenseADC2 | PA1 - ADC1              |
| PWM3 w/Sensors    | 42 PWM3H      | PA9 – TIM1-CH2          |
|                   | 35 PWM3L      | PB14 – TIM1-CH2N        |
|                   | 10 BEMFADC3   | PC2 - ADC12             |
|                   | 11 CSenseADC3 | PC3 - ADC13             |
| PWM4 w/Sensors    | 43 PWM4H      | PA10 - TIM1-CH3         |
|                   | 36 PWM4L      | PB15 - TIM1-CH3N        |
|                   | 8 BEMFADC4    | PC0 - ADC10             |
|                   | 9 CSenseADC4  | PC1 - ADC11             |
| HALL Sensors      | 22 HALL1ADC   | PA6 – TIM3 – CH1 / ADC6 |
|                   | 23 HALL2ADC   | PA7 – TIM3 – CH2 / ADC7 |
|                   | 26 HALL3ADC   | PB0 – TIM3 – CH3 / ADC8 |
| Voltage In Sensor | 20 DCADC      | PA4 - ADC4              |
| Resolver          | 27 ResolverIn | PB1 – ADC9 / PWM        |
| Temperature 1     | 25 TempADC1   | PC5 - ADC15             |
| Temperature 2     | 24 TempADC2   | PC4 - ADC14             |
| End point 1       | 38 EP1        | PC7                     |
| End point 2       | 39 EP2        | PC8                     |
| Ethernet          | 44 ETHINT     | PA11                    |
|                   | 45 ETHReset   | PA12                    |
|                   | 50 ETHCS      | PA15                    |
|                   | 55 ETHSCLK    | PB3 SPI1 or 3           |
|                   | 56 ETHMOSI    | PB4 SPI1 or 3           |
|                   | 57 ETHMISO    | PB5 SPI1 or 3           |
| RS-485            | 54 RS485DE    | PD2                     |
|                   | 58 RS485Tx    | PB6 TX1                 |
|                   | 59 RS385Rx    | PB7 RX1                 |
| Spare SPI         | 51 SCK3       | PC10                    |
|                   | 52 MISO3      | PC11                    |
|                   | 53 MOSI3      | PC12                    |
| Spare CAN         | 61 CAN1RX     | PB8                     |
|                   | 62 CAN1TX     | PB9                     |
| Spare             | 33 PB12       |                         |
|                   | 40 PC9        |                         |
|                   | 28 PB2        |                         |

## **PWM Driver 1**

This show the schematics for PWM1 and associated current sensor, BEMF Sensors, connectors and protection logic.



PWM Driver 1,2,3 & 4 are identical, so only PWM Driver 1 is annotated here.

The Gate Driver shown are IR2103S, but the actual circuit will be using IR2101S. IR2101, IR2102 & IR2103 are pin compatible and identical with exception of input logic. IR2101 is better suited for

connection to a modern PWM driver, while IR2103 can use a combined input line as it invert the LIN.

T1 & T2 are IRF7862 rated at 30V, 21A. These are HEXFET's in SO8 packages that have a large range of pin-compatible alternatives.

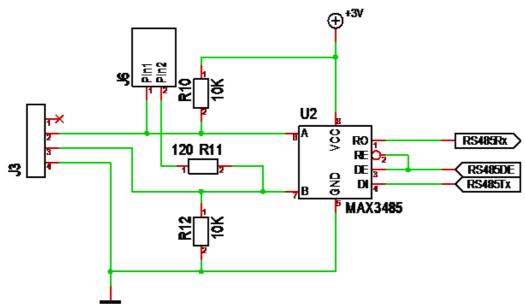
R1 is the 0.001 currents shunt that is measured by the zero-drift current sensor INA210. R16 & C5 form a low-pass filter to remove as much noise as possible. INA210 is pin compatible with a range of sensors using different amplifications.

R20, R21 & C28 is a current splitter & low pass filter for BEMF sensing.

X8 is the 1.27 pitch connector making signals available for scopes etc.

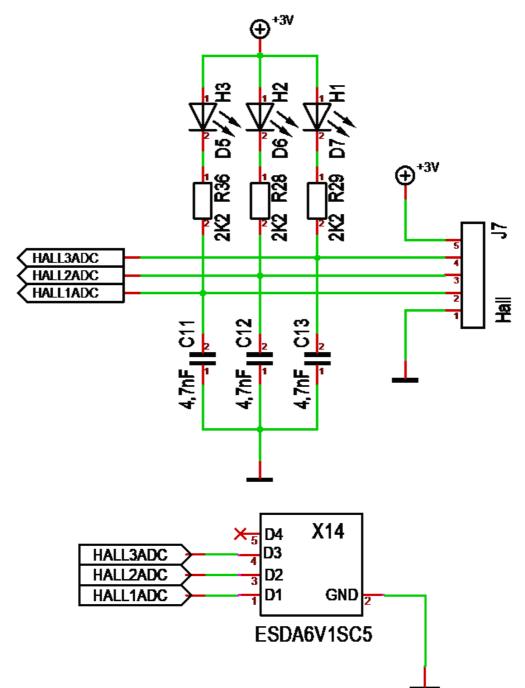
X2 is a 6.1V suppression diode used on all signals connected to the MCU for protection.

### **RS485**



Classic RS485 transceiver based on MAX3485. This is a 3.3V version of the more known MAX485.

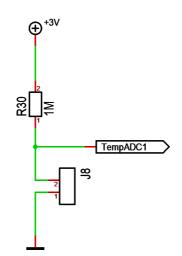
**Hall Sensors** 



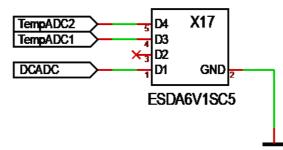
Hall sensors have a separate connector that provided 3.3V & GND out and 3 x Hall Sensor's in. The Led's will light up as the sensor input's are low. The capacitors and suppression diodes should prevent pulses.

Hall sensors are connected to Timer 3, channel 1,2 &3 where they can be counted directly by the timer logic.

#### **Temperature Sensor**

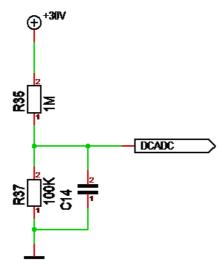


Temperature Sensor 1 & 2 are identical, only #1 is annotated here. This is a basic current splitter with the temperature sensor as the 2<sup>nd</sup>, variable resistor. The intention is that one (or both) sensors are located between the HEXFET's and the heatsink.



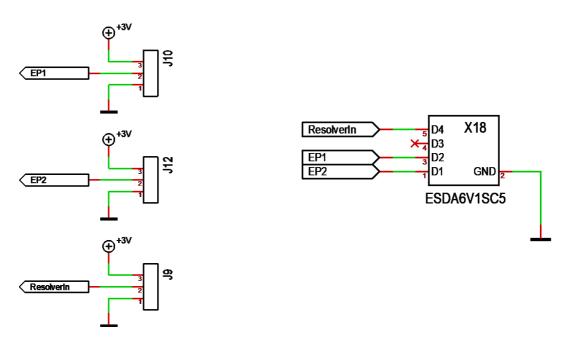
This illustrate the suppression diodes for Temperature sensor 1,2 and DC Voltage Sensor.

### DC Voltage Sensor's



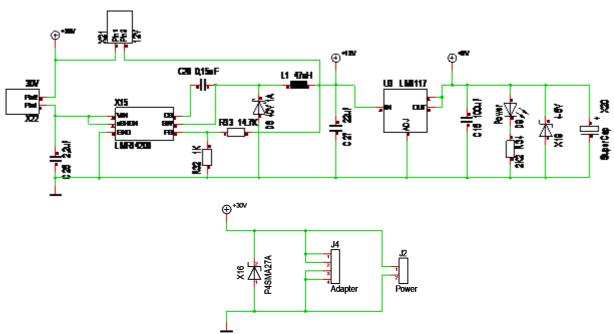
DC Voltage Sensor is a classic voltage splitter with a low pass filter and suppression diode connected to an ADC. By design this should drop several seconds before the 3.3V to the MCU drops out due to the supercap on the 3.3V PSU. This gives us the capability to monitor power drops that otherwise would reboot the MCU.

### **End Point & Resolver**



Endpoint1, Endpoint2 and Resolver uses the same design with a connector consisting of the signal, 3.3V and GND. The only added logic is the suppression diode.

#### PSU



The PSU provides 3 voltages. (1) is the raw input voltage used on the motor. This must be 12-24V. (2) is the 12V used on the Gate Driver logic provided either by direct input or by using the DC-DC converter. (3) is a 3.3V PSU provided by a classic LM1117.

A supercap on the 3.3V (roght top) will function as a battery and keep the MCU alive a few seconds after a power drop. The adapter (bottom) allows an external battery, capacitor or break resistor to be connected.

Jumpers are added to support input voltages as low as 11.1V from LIPO batteries. The circuit can support 30V if you replace the X16 suppression diode that otherwise will activate at ca 27V.

## BOM

| C1  | 100nF                      | PWM1 page 2 |
|-----|----------------------------|-------------|
| C10 | VCAP 2.2uF                 | MCU page 1  |
| C11 | 4.7nF                      | Page 4      |
| C12 | 4.7nF                      | Page 4      |
| C13 | 4.7nF                      | Page 4      |
| C14 | 2.2nF                      | Page 4      |
| C15 | 100uF                      | Page 5      |
| C2  | 100nF                      | PWM2 page 2 |
| C26 | 0,15uF                     | Page 5      |
| C27 | 22uF                       | Page 5      |
| C28 | 2.2nF                      | Page 4      |
| C29 | 2.2nF                      | Page 4      |
| C3  | 100nF                      | PWM3 page 2 |
| C30 | 2.2nF                      | Page 4      |
| C31 | 2.2nF                      | Page 4      |
| C4  | 100nF                      | PWM4 page 2 |
| C5  | 2.2nF                      | Page 4      |
| C6  | 2.2nF                      | Page 4      |
| C7  | 2.2nF                      | Page 4      |
| C8  | 2.2nF                      | Page 4      |
| C9  | VCAP 2.2uF                 | MCU page 1  |
| D1  | US1M                       | PWM1 page 2 |
| D10 | Led                        | MCU page 1  |
| D11 | Led                        | MCU page 1  |
| D12 | Led                        | MCU page 1  |
| D2  | US1M                       | PWM2 page 2 |
| D3  | US1M                       | PWM3 page 2 |
| D4  | US1M                       | PWM4 page 2 |
| D5  | Hall sensor Led            | Page 4      |
| D6  | Hall sensor Led            | Page 4      |
| D7  | Hall sensor Led            | Page 4      |
| D8  | 40V 1A TVS Diode           | Page 5      |
| D9  | Power Led                  | Page 5      |
| J1  | 4 x Motor Screw Connector  | Page 2      |
| J10 | 3 pin 2.54 pitch connector | Page 4      |
| J11 | 3 pin 2.54 pitch connector | Page 4      |
| J13 | 2 pin 2.54 pitch connector | Page 4      |
| J2  | 2 x Screw comnnector       | Page 2      |
| J3  | 4 pin 2.54 pitch connector | Page 3      |
| J4  | 2.54 pitch male pin header | Page 2      |

| J6  | 1.27 pitch jumper          | Page 3      |
|-----|----------------------------|-------------|
| J7  | 5 pin 2.54 pitch connector | Page 4      |
| J8  | 2 pin 2.54 pitch connector | Page 4      |
| J9  | 3 pin 2.54 pitch connector | Page 4      |
| L1  | 47uH 1A                    | Page 5      |
| Q1  | 8 Mhz Murata x-tal         | MCU page 1  |
| R1  | 1mOhm Shunt Resistor       | PWM1 page 2 |
| R10 | 10K bias                   | Page 3      |
| R11 | 120 Ohm Terminator         | Page 3      |
| R12 | 10K bias                   | Page 3      |
| R13 | 1mOhm Shunt Resistor       | PWM2 page 2 |
| R14 | 1mOhm Shunt Resistor       | PWM3 page 2 |
| R15 | 1mOhm Shunt Resistor       | PWM4 page 2 |
| R16 | 10K                        | Page 4      |
| R17 | 10K                        | Page 4      |
| R18 | 10K                        | Page 4      |
| R19 | 10K                        | Page 4      |
| R2  | 47                         | PWM1 page 2 |
| R20 | 1M                         | Page 4      |
| R21 | 100K                       | Page 4      |
| R22 | 1M                         | Page 4      |
| R23 | 100K                       | Page 4      |
| R24 | 1M                         | Page 4      |
| R25 | 100K                       | Page 4      |
| R26 | 1M                         | Page 4      |
| R27 | 100K                       | Page 4      |
| R28 | 2.2K Led Resistor          | Page 4      |
| R29 | 2.2K Led Resistor          | Page 4      |
| R3  | 47                         | PWM1 page 2 |
| R30 | 1M                         | Page 4      |
| R31 | 10K Pull-Down              | MCU page 1  |
| R32 | 1K                         | Page 5      |
| R33 | 14,7K                      | Page 5      |
| R34 | 2.2K Led Resistor          | Page 5      |
| R35 | 1M                         | Page 4      |
| R36 | 2.2K Led Resistor          | Page 4      |
| R37 | 100K                       | Page 4      |
| R38 | 1M                         | Page 4      |
| R39 | 10K Pull-Up                | MCU page 1  |
| R4  | 47                         | PWM2 page 2 |
| R40 | 2.2K Led resistor          | MCU page 1  |
| R41 | 2.2K Led resistor          | MCU page 1  |

| R42  | 2.2K Led resistor      | MCU page 1  |                       |
|------|------------------------|-------------|-----------------------|
| R5   | 47                     | PWM2 page 2 |                       |
| R6   | 47                     | PWM3 page 2 |                       |
| R7   | 47                     | PWM3 page 2 |                       |
| R8   | 47                     | PWM4 page 2 |                       |
| R9   | 47                     | PWM4 page 2 |                       |
| S1   | IR2103S                | PWM1 page 2 |                       |
| S2   | IR2103S                | PWM2 page 2 |                       |
| S3   | IR2103S                | PWM3 page 2 |                       |
| S4   | IR2103S                | PWM4 page 2 |                       |
| SWD1 | 1.27 pitch Connector   | MCU page 1  |                       |
| SWD2 | 1.27 pitch Connector   | MCU page 1  |                       |
| T1   | IRF7862                | PWM1 page 2 |                       |
| T2   | IRF7862                | PWM1 page 2 |                       |
| Т3   | IRF7862                | PWM2 page 2 |                       |
| T4   | IRF7862                | PWM2 page 2 |                       |
| T5   | IRF7862                | PWM3 page 2 |                       |
| Т6   | IRF7862                | PWM3 page 2 |                       |
| T7   | IRF7862                | PWM4 page 2 |                       |
| Т8   | IRF7862                | PWM4 page 2 |                       |
| U1   | STM32F405RG            | MCU page 1  |                       |
| U2   | MAX3485                | Page 3      |                       |
| U3   | LM1117                 | Page 5      |                       |
| X10  | 1.27 pitch Male Header | Page 2      |                       |
| X11  | 1.27 pitch Male Header | Page 2      |                       |
| X12  | ESDA6V1SC5             | Page 2      |                       |
| X13  | ESDA6V1SC5             | Page 2      |                       |
| X14  | ESDA6V1SC5             | Page 4      |                       |
| X15  | LMR14206               | Page 5      |                       |
| X16  | P4SMA27A               | Page 2      | 27V Suppression diode |
| X17  | ESDA6V1SC5             | Page 4      |                       |
| X18  | ESDA6V1SC5             | Page 4      |                       |
| X19  | 4+ V Suppression Diode | Page 5      |                       |
| X2   | ESDA6V1SC5             | Page 2      |                       |
| X20  | Supercap               | Page 5      |                       |
| X21  | 12V 1.27 pitch Jumper  | Page 5      |                       |
| X22  | 30V 1.27 pitch Jumper  | Page 5      |                       |
| X3   | ESDA6V1SC5             | Page 2      |                       |
| X4   | INA210                 | Page 4      |                       |
| X5   | INA210                 | Page 4      |                       |
| X6   | INA210                 | Page 4      |                       |
| X7   | INA210                 | Page 4      |                       |

| X8 | 1.27 pitch Male Header | Page 2 |  |
|----|------------------------|--------|--|
| X9 | 1.27 pitch Male Header | Page 2 |  |